# **LOTUS CONTROLLERS**









### LOTUS ENGINEERING SUPPLIES A RANGE OF CONTROLLERS FOR A WIDE RANGE OF CLIENT APPLICATIONS

Control systems are an integral aspect of today's vehicles, from safety, stability and security systems, through all aspects of powertrain and propulsion to the total human machine interface. Increasingly, with the adoption of these control technologies, vehicle attributes and product differentiation is often defined by electronic systems and settings.

We can define and implement the complete control system requirements for production, developing software and integrating hardware elements across the whole vehicle for improved efficiency and functionality, promoting brand character.

Our own Lotus control systems offer production solutions for lower investment, faster to market options that are flexible and adaptable for a wide range of client applications. We understand design of control systems for safety and durability and they have proven operation in a range of Lotus vehicles (including Elise, Exige and the Evora).

Lotus is partnered with Efi Technology which has a history of providing state-of-the-art engine controllers, together we can deliver bespoke hardware and software solutions to a customers specification, from design and development, through to calibration and certification including On Board Diagnostics (OBD) strategy.

### BENEFITS OF USING LOTUS CONTROLLERS

We have expertise in complex electronics across all vehicle systems and can use our own technology to work with, or substitute for, individual systems' controllers within engineering programmes for cost-effective results. Our skills and experience also allow fast and effective integration of many separate vehicle systems, even if they have not previously been used together for an application.

- Lotus controllers are fully compatible with latest emissions diagnostics, EMC and safety requirements
- Lotus controllers can be used in a range of applications including cars, motorbikes, marine and automatic transmissions
- Lotus controllers can be used in electric and hybrid vehicles
- Lotus controllers can be provided at shorter lead times for prototype applications
- Lotus controllers can be integrated with whole vehicle systems, sensors and actuators from any source

### TRANSMISSION CONTROLLER UNIT (TCU)

The Lotus TCU has been developed to meet the requirements of complex and advanced modern automatic transmissions such as the new Lotus Intelligent Precision Shift (IPS) gearbox fitted to the Lotus Evora. The TCU supports a range of automatic transmissions including:

- Conventional torque converter automatics
- Automated manual transmissions
- Dual clutch transmissions

#### **LOTUS T6 ENGINE CONTROL UNIT (ECU)**

The T6 controller is the latest in a line of Lotus ECU controllers that have proven operation in Lotus vehicles as well as EV and HEV applications

- Lotus T6 Controller is ODB2 Compliant
- Can be used in electric and hybrid vehicle applications
- Supports engines up to six cylinders
- Can be used in prototype and research and development applications

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	TCU	T6 ECU
Main CPU	MPC5534 80MHz	MPC5534 80MHz
ETB safety CPU		4/8 Mhz, 8Kb Flash, 256 Byte Ram
RAM	64Kb	64Kb
FLASH	1MB	1MB
Mating connectors	80 way (52+28) PCB connector	Two 48 way Molex CMC connector
	52 way connector (4 hi current and 48 low current)	One 32 way Molex CMC connector
	28 way connector (low current)	
Environmental	Minus 40 to 105 °c (operating and storage)	Minus 40 to 70 °c (operating) Minus 40 to 90 °c (storage)
Vibration	Body mounted device	Body mounted device
Electrical specification	12 Volts nominal, 6 Volts min, 15 Volts max	12 Volts nominal, 6 Volts min, 15 Volts ma
Digital outputs	High current, independent high side x1	Low current x4
	High current, common high side x5	High current x12
	Low side x4	Injectors x8
	High side x1	Relay x4
	Main relay x1	Main relay x1
		Ignition x8
		Heater x4
Analogue inputs	Pull-up/down, general purpose, NTC sensor	Pull up/down x14
	input x7	NTC x5
	Battery x2	Lambda x4
		Battery x2
		Knock x2
Digital inputs	VR/Hall (EM) x1	VR/Hall x4
	Hall Effect (HE) x10	Hall x7
	Variable resistance (SP) x2	Logic x7
	Digital output LED(HL) x6	
Voltage references and ground		
Voltage reference	4x analogue 2x digital	4x analogue 1x digital
GND - Analogue (AGND)	6 analogue ground	8 analogue ground
GND - Digital (GND)	5 digital ground	11 digital ground
GND - Power (GNDPOW)	4 power ground	GND-KNK x2
CAN lines	2	2
DC motor driver	3 H-Bridge	ETB driver x2
Additional features		Baro pressure sensor (on board)

### LIGHTWEIGHT ARCHITECTURES - EFFICIENT PERFORMANCE - ELECTRICAL AND ELECTRONIC INTEGRATION - DRIVING DYNAMICS

















## UNITED KINGDOM

Potash Lane Hethel, Norwich NR14 8EZ

Phone: +44 (0)1953 608423 eng-uk@lotuscars.com

## USA

1254 N. Main Street Ann Arbor MI 48104

Phone: +1 734 995 2544 eng-usa@lotuscars.com

## CHINA

7th Floor, New Jinqiao Tower No.28 New Jinqiao Road, Pudong, Shanghai. PR CHINA 201206

Phone: + 86 (21)5030 9990 eng-china@lotuscars.com